# Module Type 4 Channels Temperature Controller **User Manual**

(ST323B 4 Channels Series)

(Applied to ST323B A Version)



#### Features:

- O Multiple RTD signal types for option, with isolation between signal inputs
- able to connect grounding probe; three wire RTD input.
- ⊙ With many functions, measured display, control output, RS485 communication, etc.
- ⊙ Optional many types of PID arithmetic, and with auto-tuning function.
- ⊙ Using for industrial machinery, machine tools, measuring instruments.
- ⊙With limiting target value setting function

National High-tech Enterprise/ National Standard Drafting Unit



Version code: KKST323B-A01E-A/0-20230323 Hotline: 400-8866-986

The instruction explain ST323B series instrument settings, connections,name and etc, please read carefully before you use the temperature controller. Please keep it properly for necessary reference.

## Safe Caution

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- 1) When the failure or abnormal of products lead to a system of major accidents, please set the proper protection circuit in the external.
- 2) Please don't plug in before completing all the wire. Otherwise it may lead to electric shock,
- 3) Not allow to use outside the scope of product specification, otherwise it may lead to fire, fault.
- Not allow to use in the place where is inflammable and explosive gas.
- 5) Do not touch power terminal and other high voltage part when the power on, otherwise you may get an electric-shock.

  6) Do not remove,repair and modify this product,otherwise it may lead to electric shock, fire,
- fault.

#### **∆** Caution

- 1) The product should not be used in a nuclear facility and human life associated medical
- 2) The product may occur radio interference when it used at home. You should take adequate
- The product get an electric shock protection through reinforced Insulation. When the product is embedded in the devices and wiring, please subject to the specification of embedded
- In order to prevent surge occurs, when using this product in the place of over 30m indoor wiring and wiring in outdoor, you need to set the proper surge suppression circuitry.
- 5) The product is produced based on mounting on the disk. In order to avoid to touch the wire connectors, please take the necessary measures on the product.
  6) Be sure to observe the precautions in this manual, otherwise there is a risk of a major injury
- When wiring, please observe the local regulation.
- To prevent to damage the machine and prevent to machine failure, the product is connected with power lines or large capacity input and output lines and other methods please install proper capacity fuse or other methods of protection circuit.
- Please don't put metal and wire clastic mixed with this product, otherwise it may lead to electric shock, fire, fault.
- 10) Please tighten screw torque according to the rules.If not,it may lead to electric shock and
- 11) In order not to interfere with this products to dissipate heat, please don't plug casing around the cooling vent hole and equipment.
- 12) Please don't connect any unused terminal.
  13) Please do the cleaning after power off, and use the dry cleaning cloth to wipe away the dirt. Please don't use desiccant, otherwise, it may casue the deformation or discoloration of the
- Please don't knock or rub the panel with rigid thing.
- 15) The readers of this manual should have basic knowledge of electrical control, computer and
- The illustrations, data examples and picture examples used in this manual are recorded for the convenience of understanding the manual, and are not guaranteed to be the results of
- 17) In order to use this product with safety for long-term,regular maintenance is necessary. The life of some parts of the equipments are by some restrictions, but the performance of some
- will change for using many years.

  18) Without prior notice, the contents of this manual may will be change. We hope these is no any loopholes, if you have questions or objections, please contact us.
- 19) Our company will not liable for any indirect losses suffered by users or third parties, such as the results impact of using this product, unpredictable product defects, imitations of this product and other indirect losses.

#### ⚠ Caution of Install & Connection

#### 1.Installation

- 1.Installation

  1) This product is used in the following environmental standards. ( IEC61010-1) [Overvoltage category □ ⋅ class of pollution 2].

  2)This product is used in the following scope:environment, temperature, humidity and environmental conditions. Temperature:0~50 ℃; humidity:45~85%RH; Environment condition:Indoor warranty. The altitude is less than 2000m.

  3) Please avoid using in the following places:
  The place will be dew for changing temperature; with corrosive gases and flammable gas; with vibration and impact; with water, oil, chemicals, smoke and steam facilities with Dust, salt, metal powder; and with clutter interference, static electric and magnetic fields, noise; where has air conditioning or heating of air blowing directly to the site; where will be illuminated directly by sunlight; where accumulation of heat will happen caused by radiation. accumulation of heat will happen caused by radiation.
  4) On the occasion of the installation, please consider the following before
- installation.
  In order to protect heat saturated, please ensure adequate ventilation space.

In order to protect heat saturated, please ensure adequate ventilation space. Please consider connections and environment, and ensure that the products below for more than 50mm space. Please avoid to installed over the machine of the calorific value (Such as heaters, transformer, semiconductor operations, the bulk resistance). When the surrounding is more than 50, please using the force fan or cooling fans. But don't let cold air blowing directly to the product. In order to improve the anti - interference performance and security, please try to stay away from high pressure machines, power machines to install.

Don't install on the same plate with high pressure machine and the product. The distance should be more than 200mm between the product and power line.

The power machine shall be installed at a distance as far as possible.

- 2. Cable caution:
- 1) Please use specified compensation wire in the place of TC input;Please use insulated TC if the measured device is heated metal.The influence of external resistance is about 0.3 μ V/Ω<sub>o</sub>
- 2) Please use the cable of lesser resistance in the place of RTD input,and the cable(3 wire) must be no resistance difference,run in parallel, and the single wire resistance is less than  $10\Omega.\,$
- 3) In order to avoid the effect of noise, please put the input dignal away from meter cable, power cable, load cable to wiring.

  4) In order to reduce the power cables and the load power cables on the effect
- a) in order to reduce the power capies and the load power capies of the end of this product, please use noise filter in the place where easy to effect. You must install it on the grounding of the disk if you use the noise filter, and make the wiring to be shortest between noise filter output side and power connectors. Don't install fuse and switch on the wiring of noice filter output side attentions it will reduce the effect of poice filter.
- side, otherwise it will reduce the effect of noise filter.

  5) It takes 5s from input power to output. If there is a place with interlocking
- traces a form interior power to duptur. In the is a place with interior actions circuit signal, please use timer relay.

  6) Please use twisted pair with a shield for analog output line, can also connect the common-mode coil to the front-end of the signal receiving device to suppress line interference if necessary, to ensure the reliability of signal.

  7)Please use twisted pair with a shield for remote RS485 communication cable,
- and deal with the shield on the host side earth, to ensure the reliability of signal.

  8) This product don't have the fuse; please set according to rated voltage 250V,rated current 1A if you need; fuse type:relay fuse.

  9) Please use suitable slotted screwdriver and wire.

Terminal distance: 5.0mm. Screwdriver size: 0.6X3.5, length of slotted screwdriver >130mm. Recommended tightening torque: 0.5N.m.

Proper cables: 0.25  $^{\sim}$  1.65mm single cable/multiple core cable 10) Please don't put the crimp terminal or bare wire part contact with adjacent

## II. Model Illustration



# III Model Description

III. Model Description								
NO	Model	Input	Туре		~ OUT4 ol Output	RS485		
		TC	RTD	SSR	Transistor	communication		
1	ST323B-DF-4PS8-□		•	•		•		
2	ST323B-DF-4PT8-□		•		•	•		
3	ST323B-DF-4PS-□		•	•				
4	ST323B-DF-4PT-□		•		•			

# Connector description (optional):

NO	Connector Name	Ordering code	See the installation		
1	DIN rail connector	DEKW3.81-5P-BUS1	dimension drawing		
2	Plug in connector	DEKW3.81-5P-BUS2	in the part V		

#### IV. Specifications

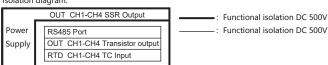
## 1. Electrical parameters:

1. Licetifear parameters.							
Sample rate	1 times per second per channel						
Power supply	DC 24V						
Power consumption	< 6VA						
Environment	Indoor use,Temperature: 0 ~ 50°C no condensation, Humidity: < 85%RH, altitude<2000m						
Storage environment	-10 ~ 60°C, no condensation						
SSR output	DC 24V pulse level, load<20mA						
Current output	DC 24 DC 100mA per channel						
Communication port	RS485 port, Modbus-RTU procotol						
Insulation impedance	Input, output, power cabinet > 20MΩ						
ESD	IEC/EN61000-4-2 Contact ±4KV /Air ±8KV perf.Criteria B						
Voltage drop & short interruption immunity	IEC/EN61000-4-29 0% ~ 70% perf.CriGTEria B						
Dielectric strength	DC500V 1min						
Total weight	About 400g						
Shell material	PA66-FR (Flame Class UL94V-0)						
Panel material	PVC film and PEM silicone key						
Power-off data protection 10 years , times of writing: 1 million times							
Safety Standard	IEC61010-1 Overvoltage category $\Pi_{,}$ pollution level 2, level $\Pi_{,}$ (Enhanced insulation)						

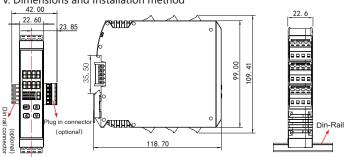
#### 2. Measurement signal parameter

Input Type		Symbol	Measurement Range	Resolution	Accuracy	Input impedance/ Auxiliary current	Commincation Code	
	PT100	PT1	PEI	-200.0 ~ 600.0	0.2℃	0.5%F.S±0.3℃	0.33mA	8
	P1100			-200 ∼ 600	1°C	0.5%F.S±3digits	0.33mA	21
	JPT100	OO JPT1 JFL		-200.0 ~ 500.0	0.2°C	0.5%F.S±0.3℃	0.33mA	9
		JPT2	72F5	-200 ∼ 500	1°C	0.5%F.S±3digits	0.33mA	22
RTD	CU50	CU51	CUST	-50.0 ∼ 150.0	0.2℃	0.5%F.S±4℃	0.33mA	10
	C030	CU52	CUSZ	-50 ∼ 150	1°C	0.5%F.S±4℃	0.33mA	23
	CU100	CU101	CUOI	-50.0 ∼ 150.0	0.2℃	0.5%F.S±2℃	0.33mA	11
	C0100	CU102	COOS	-50 ∼ 150	1°C	0.5%F.S±2℃	0.33mA	24
	$0 \sim 400\Omega$		r.E	-1999 ~ 9999	12bit	0.5%F.S±3digits	0.33mA	13

3. Isolation diagram:



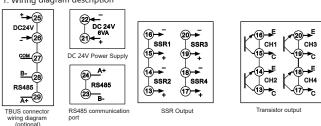
#### V. Dimensions and Installation method

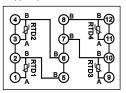


Note: 35mm standard clamping rail is not equipped, and the product must be fixed on the clamping rail. DIN rail connector and plug-in connector are not equipped in the factory, and can be selected by the customer.

## VI. Connection Diagram

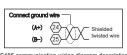
#### 1. Wiring diagram description

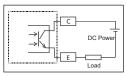




RTD Input

# 2. Examples of partial wiring diagram

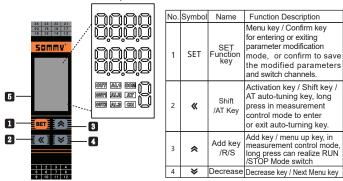




RS485 communication wiring diagram description

In case of any change, please subject to the wiring diagram on the actual product

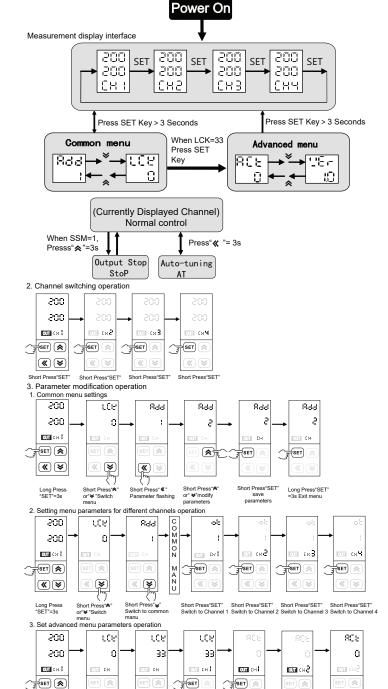
## VII. Name of universal panel

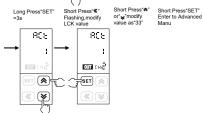


No.	Symbol	Name	Function Description
	CH)	СН	Channel indication window
5	TUO	OUT	OUT indication, when there is display, it indicates the current channel control is ON, when there is no display, it indicates that the current channel control is OFF
	AT instruction. When there is a display, it indicates the		AT instruction. When there is a display, it indicates that the current channel is performing auto-turning. When there is no display, it indicates that there is no auto-tuning or auto-tuning is complete.
	COM	СОМ	Communication status indicator

## VIII. Operation Process and Menu Illustration

#### 1. Operation process & method





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Short Press"SET" Save parameter

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a. In normal measurement control mode after power on, press and hold the "SET" key for more than 3 seconds to enter the menu parameter viewing mode, short press "SET" key to switch the display channel, the channel number is displayed in the CH indication window, and the panel display correspond to the channel number:

Short Press"SET Switch Channel

Switch Channe "CH2"

**«** »

b. In the menu view mode, short press "♠" or "♦" key check the common menu parameters

circuiany. c.ln the menu view mode, short press the " $\langle\!\langle$ " key to flash the viewed menu parameter value to enter the parameter modification mode, and each short press can move one bit to the left; this

cycle.
d. In the parameter modification mode, press the " 🛠 " or " 🔖 " key once to increase or

decrease the flashing data bit by one.
e. In the parameter modification mode, shortly press the "SET" key after the parameter is modified to save the modified parameter and long press "SET" exit to the menu view mode.
f. In normal measurement control mode, press and hold the " " key for more than 3 seconds to enter the PID auto-tuning state corresponding to the channel.

h. In the normal measurement control mode, press and hold the " 🛠 " key for more than 3 seconds to enter or exit the running or stop mode corresponding to the channel; the stop mode SV window displays "STOP"

Note that the SSM should enable panel operation. "STOP" is displayed.

## 

No		Hide p	arameters according to model		
	Symbol	Name	Illustration	Setting range	Factor setting
1		PV	Measuring display value,it will flash or display LLLL/ HHHH when the value overflow measure range.Unit: $\mathbb{C}$ / $\mathbb{F}$ or no unit	Refer to measured	NO
2		SV	Control item setting value	signal table	
4	108	LCK	Channel number display window  Lock function; 0001: SV value can not be changed; 0010: menu setting value can be read only; 023: advanced my value can be read only;	1~F 0~9999	0
5	833	ADD	0033: advanced menu can beaccessed; 0123: menu restore factory setting Communication address	1~247	1
6	588	BAD	RS485 communication baud rate 4.8 (0): 4800; 9.6 (1):9600; 19.2 (2):19200; 38.4 (3):38400	0~3	1
7	P-63	PRTY	Communication parity check setting 0: NO 1: ODD 2: EVEN	0~2	0
8	886C	DATC	Communication data transport sequence 000; 1st bit function reserved; 2nd bit is byte sequence exchange; 3rd bit function reserved.	Refer to COM protocol note(3)	0
9	ob	ОТ	Contral mode, 0:ON/OFF heating control,1: PID heating control 2: ON/OFF cooling control 3:Reversed 4: Over temperature cooling output 5. PID cooling	0~5	1
10	ρ	Р	Proportional band, the smaller the value is, the faster the system responds, otherwise, it is slower. When P=0, no PID control, unit same as PV	0~9999	30
11	;	ı	Integral time, the smaller the value is, the stronger the integral action is, otherwise, it is weeker. When I=0, no integral action, unit: s.	0~9999	120
12	ತ	D	Differential time: reduce the differential action to an appropriate value to prevent system oscillation. The larger the value, the stronger the differential	0~9999	30
13	8-5	A-M	Auto-manual control switch, AUTO(0): auto	AUTO~AM	AUTO
14	CP	CP	control only; MAN(1): manual control only; OUT1 control cycle, 1: SSR control output,	1~200	1
15	đb	DB	4-200: relay control output. Unit:s  ON/OFF control hystersis(positive and negative numbers work the same); when OT=3, it is the dead zone for cooling control(positive and negative numbers work differently);after change the INP setting, please change this parameter according	0~1000	5
16	laP	INP	to the decimal point position.  Optional input signal, refer to input signal parameters table. Note: after selecting the	Refer to measured	PT2
17	25	PS	signal, pls set corresponding parameters  Amend value, display value= actual measured	signal specification -1000 ~ 1000	0
		ed Mer			
18	805	ACT	Control execution mode, 0~1: SSR output control or transistor output  Decimal point setting is effective under the linear	0~1	0
19	d2	DP	PV fuzzy tracking value,properly set this value on some	0~3	0
20	dbr	DTR	occasions, it can get a more stable control display value, this value is unrelated with actual measured value. Note: after setting this value, when alarm setting value is equal to SV setting value, alarm output operation is subject to actual measured value. Set as 0 to close this function. The temperature input unit: Fahrenheit or Celsius. The linear signal input unit: Engineering Digits	0.0~2.0 0~20	1.0
21	SSA	SSM	Press the key on the panel to switch the RUN / STOP, 0: prohibited, 1:OpenThis setting is only related to panel operation, not related with communication	0 ~ 1	0
22	SUL	SLL	Lower limit of the target SV range. Over this limit, SV can't be modified	FL~FH	
23	SUH	SLH	High limit of the target SV range. Over this limit, SV can't be modified	FL~FH	
24	FL	1.	Measure range low limit,the setting value must be smaller than measure range high limit.  Measure range high limit,the setting value	Refer to measured signal	
25	FH		must be more than measure range low limit.	parameter table	
26 27		FH	Filter coefficient of each channel, the larger		
	PE Pu	FT	Filter coefficient of each channel, the larger the value, the stronger the filtering effect.	0 ~ 255 0 ~ 9999	10
28	95 95 960		the value,the stronger the filtering effect.  Compressor start delay time, unit: s  PID type selection 0 (FUZ): advanced fuzzy PID	0 ~ 255 0 ~ 9999 FUZ/STD	0
	PE	FT PT PDC	the value, the stronger the filtering effect.  Compressor start delay time, unit: s PID type selection 0 (FUZ): advanced fuzzy PID algorithm;1 (STD): ordinary PID algorithm  Temperature unit setting C: Celsius T: Fahrenheit, note: this unit setting is only for temperature	0~9999	0 FUZ
28	PE PaC	FT PT PDC UNIT	the value, the stronger the filtering effect.  Compressor start delay time, unit: s PID type selection 0 (FUZ): advanced fuzzy PID algorithm;1 (STD): ordinary PID algorithm  Temperature unit setting C: Celsius F: Fahrenheit,	0~9999 FUZ/STD (25) C (26) F	0 FUZ (25) (
28	Ps PdC Units	FT PT PDC UNIT	the value, the stronger the filtering effect.  Compressor start delay time, unit: s  PID type selection 0 (FUZ): advanced fuzzy PID algorithm; 1 (STD): ordinary PID algorithm;  Temperature unit setting C: Celsius F: Fahrenheit, note: this unit setting is only for temperature measurement signals  Setting parameter reserve position:0 (EEP):EEPROM with power failure protection. Description of setting parameter storage address: EEP and RAM. EEP means that the setting parameters are written into EEPROM and can be permanently saved after power failure. It is generally used for factory setting parameters of equipment. Because EEPROM has the limit of writing times, too many and too frequent writes will be damaged; RAM: it means that the parameters are stored in RAM without writing limit and will not be damaged due to frequent writing. The parameters setting will not be saved when the equipment is powered off. After power on, they will be restored to the parameters as eaved in EEPROM by the equipment manufacturer. It is usually used for parameters frequent writing when communicating with the upper computer PLC. The method of using this parameter is to set this parameter as EEP firstly. After the equipment factory has finished debugging the equipment and set the parameters, the parameters are saved in EEPROM, and then PRS is modified into RAM, and the equipment is delivered to the user for use, so as to prevent erroneous modification or long-term communication writing data from damaging EEPROM.  RUNISTOP reserve position: 0 (EEP):EEPROM with power failure protection;1(RAM); RAM without power failure protection;1(RAM); RAM w	0~9999 FUZ/STD (25) C (26) F	0 FUZ (25) 0
28 29 30	94C UAR 94G	FT PT PDC UNIT	the value, the stronger the filtering effect.  Compressor start delay time, unit: s  PID type selection 0 (FUZ): advanced fuzzy PID algorithm: 1 (STD): ordinary PID algorithm: 1 (STD): ordinary PID algorithm: 1 Temperature unit setting is only for temperature measurement signals  Setting parameter reserve position: 0 (EEP):EEPROM with power failure protection. Description of setting parameter storage address: EEP and RAM. EEP means that the setting parameters are written into EEPROM and can be permanently saved after power failure. It is generally used for factory setting parameters of equipment. Because EEPROM has the limit of writing times, too many and too frequent writes will be damaged due to frequent writing. The parameters are stored in RAM without writing limit and will not be damaged due to frequent writing. The parameters setting will not be saved when the equipment is powered off. After power on, they will be restored to the parameters saved in EEPROM by the equipment manufacturer. It is usually used for parameters frequent writing when communicating with the upper computer PLC. The method of using this parameter is to set this parameter as EEP fistly. After the equipment and set the parameters, the parameters are saved in EEPROM, and then PRS is modified into RAM, and the equipment is delivered to the user for use, so as to prevent erroneous modification or long-term communication writing data from damaging EEPROM.  RUNISTOP reserve position: 0 (EEP):EEPROM with mover failure protection; 1(RAM); RAM without power failure protection; 1(RAM); RAM wit	0~9999 FUZ/STD (25) C (26) F	
28 29 30 31	945 945 945	FT PT PDC UNIT	the value, the stronger the filtering effect.  Compressor start delay time, unit: s  PID type selection 0 (FUZ): advanced fuzzy PID algorithm; 1 (STD): ordinary PID algorithm  Temperature unit setting C: Celsius F: Fahrenheit, note: this unit setting is only for temperature measurement signals  Setting parameter reserve position:0 (EEP):EEPROM with power failure protection. Description of setting parameter storage address: EEP and RAM. EEP means that the setting parameters are written into EEPROM and can be permanently saved after power failure. It is generally used for factory setting parameters of equipment. Because EEPROM has the limit of writing times, too many and too frequent writes will be damaged; RAM: it means that the parameters are stored in RAM without writing limit and will not be damaged due to frequent writing. The parameters setting will not be saved when the equipment is powered off. After power on, they will be restored to the parameters saved in EEPROM by the equipment manufacturer. It is usually used for parameters frequent writing when communicating with the upper computer PLC. The method of using this parameter is to set this parameter as EEP firstly. After the equipment factory has finished debugging the equipment and set the parameters, the parameters are saved in EEPROM, and then PRS is modified into RAM, and the equipment is delivered to the user for use, so as to prevent erroneous modification or long-term communication writing data from damaging EEPROM.  RUNISTOP reserve position: 0 (EEP):EEPROM with power failure protection;1(RAM); RAM without power failure protection;1(RAM). RAM without power failure protection;1(RAM). RAM without power failure protection;1(RAM). The set RSS to RAM. When using, the upper computer SSS to RAM. When using, the upper computer SSS to RAM. When using, the upper computer SSS to RAM. When using, the super computer SSS to RAM. When using, the super computer starts/stops the instrument, which is stored in RAM. After power on again, the instrument still enter	0~9999 FUZ/STD (25) C (26) F	0 FUZ(25) Q

## IX. Key function operation

- 1. Monitoring mode operation(RUN/STOP)
- 1) SSM is set in open panel operation; Otherwise, the settings only be modified during communication.
- 2) Under the measure mode, long press \* \( \approx \) \* key to enter the STOP mode, SV willow \( \text{will be will be minimum output.} \)
  3) Under STOP mode, long press \* \( \approx \) \* key to exit STOP mode, press \* \( \approx \) \* key to modify SV value.
- 4) Under STOP mode, alarm output and analog output work normally.
- 2. PID auto-tune operation:
- 1) Before auto-tune procedure, please switch off the control output load power, or set the meter as STOP
- 2) Before auto-tune procedure. PV value should meet below condition; when it is PID heating control, PV needs to be much smaller than SV; when it is PID cooling control, PV needs to be much larger than SV.
- 3) Before auto-tune procedure, please set a proper alarm value or eliminate the alarm condition, in order to prevent the auto-tune procedure from being affected by alarm output.
- 4) Set the PID type and SV value; the factory default setting is fuzzy PID.
- 5) Set as PID control, if there is OLL & OLH output limiting, please set the output to a proper range; factory default setting is OLL=0%, OLH=100%
- 6) Exit STOP mode, or switch on the load Power, immediately long press " **«** " key to enter auto-tune mode, then the AT indicator light is on..
- 7) The auto-tune procedure will take some time, in order not to affect auto-tune result.please don't modify the parameters or power-off.
- 8) When AT light goes out, it automatically exits auto-tune mode, PID parameters will be updated automatically, and then the meter will control automatically and exactly.
- 9) During the auto-tune procedure, below actions will cause the termination of the precess, long press
- " 🕊 " key, measure beyond the scope, abnormal display, switch to STOP mode, power-off, etc.
- 10) Note: In the occasions with output limiting operation, sometimes, even if the auto-tune is carried out, the best PID parameters still cannot be obtained.
- 11) Experienced users can set a proper PID parameter according to their experience

## X. Methods of simple fault

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Display info	Method
LLLL/HHHH	Check whether the input is disconnected; check the FH value and FL value; determine whether the working environment temperature is normal; check whether the input signal selection is correct.

#### XI. Communication procotol

The device uses Modbus RTU communication protocol for RS485 half-duplex communication, read function number 0x03, write function number 0x10 or 0x06, adopt 16-bit CRC check, the device does not return check error. Data frame format:

Start bit	Data bit	Stop bit	Check bit				
1	8	1	Settings in the PRTY menu				

Communication abnormal Handling:
For abnormal response, set the highest bit of the function number to 1. For example: if the function number requested by the master is 0x03, the corresponding item of the function number returned by the slave is 0x83. Error type code:

0x01 --- Illegal function: The function number sent by the host is not supported by the device.
0x02 --- Illegal address: The register address specified by the host exceeds the allowable range of the device address.
0x03 --- Illegal value: The value of the write data sent by the host exceeds the allowable range of the device.

Communication cycle:

The communication cycle refers to the time from the completion of the master data request to the completion of the slave return data. That is: communication cycle = request data sending time + slave device reply time + response delay time + response return time. Take the 9600 baud rate as an example: the single measurement data communication period is not less than 250ms.

## 1. Read the register

Example: The host reads the integer SV1 (SV= 200)

The address code of SV1 is 0x200C, the register number is 48205,because SV1 is an integer (2 bytes) and occupies 1 data register. The memory code for decimal integer 200 is 0x00C8

	Host request (read multiple registers)												
1 2 3 4 5 6 7 8													
Device Address		High start address			Data byte length low bit	XCRC code Low bit	XCRC code High bit						
0x01	0x03	0x20	0x0C	0x00	0x01	0x4F	0xC9						

	Slave normal response (read multiple registers)												
1 2 3 4 5 6 7													
Device Function		Qty of date bytes	Data high bit	Data low bit	XCRC code	*CRC code							
		0x02	0x00	0xC8	0xB9	0xD2							

Slave abnormal response: (Read amd write registers)

	1	2	3	4	5
Abnormal	Device Address	Function Number	Error code	CRC code Low bit	CRC code High bit
Unsupported function number For example: "01" "02" "04"	0x01	0x83	0x01	0x80	0xF0
Unsupported data ADD For example: 0x2510	0x01	0x83	0x02	0xC0	0xF1
Unsupported data value	0x01	0x83	0x03	0x01	0x31

# 2. Write the register

For example: Host writes integer SV1 (SV=200)

The ADD code of SV1 is 0x200C, the register number is 48205, because SV is integer(2 byte), seizes 1 data register. The memory code of decimal integer 200 is 0x00C8

	_			-				_						
	Host request (write multi-register)													
1	2	3	4		5		6		7	8	9	1	0	11
	Function code	Start ADD High bit	Star ADI Low	)	Length		Data byte Length low bit		Data byte Length	Data high bit	Data low bit	co	CRC de v bit	XCRC code high bit
0x01	0x10	0x20	0x0	C	0x00		0x01		0x02	0x00	0xC8	0x	86	0xC8
		,	Slave	nor	mal ansv	ver	(write m	ulti	i-register	.)				
1	2	3			4		5		6		7			8
Mete	Function	n Start . High b			rt ADD Le		ata byte ength gh bit			X CF	XCRC code low bit		ЖСF high	C code
0x0	0x10	) 0x	20		0x0C		0x00		0x01	0x0	CA		0x	0A

Slave response (write multiple registers)

	1	2	3	4	5
Abnormal	Device Address	Function Number	Error code	CRC code Low bit	CRC code High bit
Unsupported function number	0x01	0x90	0x01	0x8D	0xC0
Unsupported data ADD	0x01	0x90	0x02	0xCD	0xC1
Unsupported data value	0x01	0x90	0x03	0x0C	0x01

## Host write SV (SV= 200)

Host request (write single-register)							
1	2	3	4	5	6	7	8
Meter	Function	ADD	ADD	Data	Data		XCRC code
ADD	code	High bit	Low bit	high bit	low bit	low bit	high bit
0x01	0x06	0x20	0x0C	0x00	0xC8	0x43	0x9F

Slave normal answer (write single-register)							
1	2	3	4	5	6	7	8
Meter ADD	Function code	ADD High bit	ADD Low bit	Data high bit	1	XCRC code low bit	
0x01	0x06	0x20	0x0C	0x01	0xC8	0x43	0x9F

Data address error response: (For example:Host request the Address index is 0x2510) Slave response (write single registers)

	1	2	3	4	5
Abnormal	Device Address	Function Number	Error code	CRC code Low bit	CRC code High bit
Unsupported function number	0x01	0x86	0x01	0x83	0xA0
Unsupported data ADD	0x01	0x86	0x02	0xC3	0xA1
Unsupported data value	0x01	0x86	0x03	0x02	0x61

No		
No   Address (legister futine (j)   name   Parameter Decription   Opy		
2	Read Write	Remark
3   0x2008-0x200B(48201-48204)   MV1-MV4	R	
4   0x200C~0x200F(48205~48208)   SV1~SV4   Setting Value   1   5   0x2010~0x2013(48209~48212)   RSA1~RSA4   Power switch   1   F   6   0x2014~0x2017(48213~48216)   SSM1~SSM4   Panel R/S switch   1   F   7   0x2018~0x201B(48217~48224)   SLL1~SLL4   Setting value low limit   1   F   8   0x201C~0x201F(48221~48224)   SLL1~SLL4   Setting value high limit   1   F   Reserve   9   0x2100~0x2103(48449~48452)   INP1~INP4   Input type   1   F   1   0x2108~0x2107(48453~48456)   FL1~FL4   Display low limit   1   1   1   1   1   1   1   1   1	R	2
5         0x2010-0x2013(48209-48212)         RSA1~RSA4         Power switch         1         F           6         0x2014-0x2017(48213-48216)         SSM1~SSM4         Panel R/S switch         1         F           7         0x2018-0x201B(48217-48220)         SLL1~SLL4         Setting value low limit         1         F           8         0x201C~0x201F(48221-48224)         SLH1~SLH4         Setting value high limit         1         F           Reserve           9         0x2100-0x2103(48449~48452)         INP1~INP4         Input type         1         F           10         0x2104-0x2107(48453-48456)         FL1~FL4         Display low limit         1         F           11         0x2108-0x210B(48457~48460)         FH1~FH4         Display high limit         1         I           12         0x210C-0x210F(48461~48464)         DP1~DP4         Decimal point         1         I           13         0x2114-0x2117(48469-48472)         FT1~FT4         Display liter coefficient         1         I           14         0x2112-0x211F(48493-48496)         UNIT1~UNIT4         Display liter coefficient         1         I           15         0x212C-0x212F(48493-48496)         UNIT1~UNIT4         Display Unit         1	R/W	
6 0x2014~0x2017(48213~48216) SSM1~SSM4 Panel R/S switch 1 F   7 0x2018~0x201B(48217~48220) SLL1~SLL4 Setting value low limit 1 F   8 0x201C~0x201F(48221~48224) SLH1~SLH4 Setting value high limit 1 F   Reserve   9 0x2100~0x2103(48449~48452) INP1~INP4 Input type 1 F   10 0x2104~0x2107(48453~48456) FL1~FL4 Display low limit 1 F   11 0x2108~0x210B(48457~48460) FH1~FH4 Display high limit 1 F   12 0x210C~0x210F(48461~48464) DP1~DP4 Decimal point 1 F   13 0x2110~0x2113(48465~48468) PS1~PS4 Translation correction value 1 F   14 0x2114~0x2117(48469~48472) FT1~FT4 Display filter coefficient 1 F   15 0x2118~0x211B(48473~48466) DTR1~DTR4 Display filter coefficient 1 F   16 0x212C~0x212F(48493~48496) UNIT1~UNIT4 Display tracking value 1 F   Reserve   16 0x212C~0x212F(48493~48496) PRS1~PS4 Saving address 1 F   17 0x2130~0x2133(48497~48500) PRS1~PRS4 Saving address 1 F   18 0x2134~0x2137(48501~48504) RSS1~RSS4 Saving address 1 F   19 0x2138(48505) DN Display starting 1 F   19 0x2138(48506) DNS Channel number 1 F   20 0x2139(48506) DNS Channel number 2   21 0x2200~0x2203(48705~48708) AL11~AL14 Alarm value 1 F   23 0x2204~0x2207(48709~48712) AD11~AD14 Alarm mode 1 F   24 0x2208~0x220B(48713~48716) HY11~HY14 Alarm hysteresis 1 F   25 0x220C~0x220F(48717~48720) AE11~AE14 Alarm extended mode 1 F   27 0x2304~0x2307(48965~48968) P1~P4 Proportional band 1 F   28 0x2308~0x230B(48969~48972) I1~I4 Integration time 1 F   29 0x230C~0x2313(48977~48980) CP1~CP4 Control period 1 F   29 0x230C~0x2313(48987~48984) DB1~DB2 Data bit control hysteresis 1 I   30 0x2314~0x2317(48981~48984) DB1~DB2 Data bit control hysteresis 1 I   31 0x2314~0x2317(48981~48984) DB1~DB2 Data bit control hysteresis 1 I   32 0x2318~0x2318(48985~48988) AM1~AM4 Auto-Manual switch 1 I   8	R/W	
7 0x2018~0x201B(48217~48220) SLL1~SLL4 Setting value low limit 1	R/W	6
8 0x201C~0x201F(48221~48224) SLH1~SLH4 Setting value high limit 1 FR Reserve  9 0x2100~0x2103(48449~48452) INP1~INP4 Input type 1 Inv ox2104~0x2107(48453~48456) FL1~FL4 Display low limit 1 Inv ox2108~0x210B(48457~48460) FH1~FH4 Display high limit 1 Inv ox2108~0x210F(48461~48464) DP1~DP4 Decimal point 1 Inv ox2108~0x210F(48461~48464) DP1~DP4 Decimal point 1 Inv ox2114~0x2113(48465~48468) PS1~PS4 Translation correction value 1 Inv ox2114~0x2117(48469~48472) FT1~FT4 Display filter coefficient 1 Inv ox2118~0x211B(48473~48476) DTR1~DTR4 Display filter coefficient 1 Inv ox2118~0x211B(48473~48476) DTR1~DTR4 Display tracking value 1 Inv ox2113~0x213(48497~48500) PRS1~PRS4 Saving address 1 Inv ox2133~0x2313(48497~48500) PRS1~PRS4 Saving address 1 Inv ox2133~0x2313(48501~48504) RSS1~RSS4 RUNI/STOP Saving address 1 Inv ox2133(48501~48504) RSS1~RSS4 RUNI/STOP Saving address 1 Inv ox2133(48507) DND Display starting channel number 1 Inv ox2200~0x2203(48705~48708) AL11~AL14 Alarm value 1 Inv ox2330(48506) DNS DISPlay starting channel number 1 Inv ox2333(48506) DNS DISPlay starting channel number 1 Inv ox2333(48506) DNS DISPlay starting channel number 1 Inv ox23330(48506) DNS DISPlay starting channel number 1 Inv ox2333(48506) DNS DISPlay starting channel number 1 Inv ox2333(48506) DNS DISPlay starting channel number 1 Inv ox23330(48506) DNS DISPlay starting channel number 1 Inv ox23330(48506) DNS DISPlay starting channel number 1 Inv ox23330(48506) DNS DISPlay starting channel	R/W	
Reserve	R/W	
9   0x2100~0x2103(48449~48452)   INP1~INP4   Input type   1   F	R/W	
10		
11   0x2108~0x210B(48457~48460)   FH1~FH4   Display high limit   1   1   2   0x210C~0x210F(48461~48464)   DP1~DP4   Decimal point   1   1   1   3   0x2110~0x2113(48465~48468)   PS1~PS4   Translation correction value   1   1   1   4   0x2114~0x2117(48469~48472)   FT1~FT4   Display filter coefficient   1   1   1   1   1   1   1   1   1	R/W	
12   0x210C~0x210F(48461~48464)   DP1~DP4   Decimal point   1   1   1   1   1   1   1   1   1	R/W	
13   0x2110~0x2113(48465~48468)   PS1~PS4   Translation correction value   1   1   1   1   1   1   1   1   1	R/W	
14	R/W	
The control of the	R/W	
Reserve	R/W	
16	R/W	
17		
17	R/W	
18	R/W	
19	R/W	
DNS	R/W	
21	R/W	
Reserve	R/W	
22         0x2200~0x2203(48705~48708)         AL11~AL14         Alarm value         1         I           23         0x2204~0x2207(48709~48712)         AD11~AD14         Alarm mode         1         I           24         0x2208~0x220B(48713~48716)         HY11~HY14         Alarm hysteresis         1         I           25         0x220C~0x220F(48717~48720)         AE11~AE14         Alarm extended mode         1         I           26         0x2300~0x2303(48961~48964)         OT1~OT4         Control Mode         1         I           27         0x2304~0x2307(48965~48968)         P1~P4         Proportional band         1         I           28         0x2308~0x230B(48969~48972)         I1~I4         Integration time         1         I           29         0x230C~0x230F(48973~48976)         D1~D4         Differential time         1         I           30         0x2310~0x2313(48977~48980)         CP1~CP4         Control period         1         I           31         0x2314~0x2317(48981~48984)         DB1~DB2         Data bit control hysteresis         1         I           32         0x2318~0x231B(48985~48988)         AM1~AM4         Auto-Manual switch         1         I           33         0x2324~0x2327(48997~		
23    0x2204~0x2207(48709~48712)   AD11~AD14   Alarm mode   1    1    24    0x2208~0x220B(48713~48716)   HY11~HY14   Alarm hysteresis   1    1    25    0x220C~0x220F(48717~48720)   AE11~AE14   Alarm extended mode   1    1    1    25    0x220C~0x220F(48717~48720)   AE11~AE14   Alarm extended mode   1    1    27    0x2304~0x2303(48961~48964)   OT1~OT4   Control Mode   1    1    27    0x2304~0x2307(48965~48968)   P1~P4   Proportional band   1    1    28    0x2308~0x230B(48969~48972)   I1~I4   Integration time   1    1    29    0x230C~0x230F(48973~48976)   D1~D4   Differential time   1    1    30    0x2310~0x2313(48977~48980)   CP1~CP4   Control period   1    1    31    0x2314~0x2317(48981~48984)   DB1~DB2   Data bit control hysteresis   1    32    0x2318~0x231B(48985~48988)   AM1~AM4   Auto-Manual switch   1    1    1    1    1    1    1	R/W	
24    0x2208~0x220B(48713~48716)   HY11~HY14   Alarm hysteresis   1    1    25    0x220C~0x220F(48717~48720)   AE11~AE14   Alarm extended mode   1    1    1    2    2    2    2    2	R/W	4)
25  0x220C~0x220F(48717~48720)	R/W	9
Reserve   26   0x2300~0x2303(48961~48964)   OT1~OT4   Control Mode   1   I   27   0x2304~0x2307(48965~48968)   P1~P4   Proportional band   1   I   28   0x2308~0x230B(48969~48972)   I1~I4   Integration time   1   I   29   0x230C~0x230F(48973~48976)   D1~D4   Differential time   1   I   30   0x2310~0x2313(48977~48980)   CP1~CP4   Control period   1   I   31   0x2314~0x2317(48981~48984)   DB1~DB2   Data bit control hysteresis   1   32   0x2318~0x231B(48985~48988)   AM1~AM4   Auto-Manual switch   1   I   Reserve   33   0x2324~0x2327(48997~49000)   ACT1~ACT4   Output type   1   F	R/W	(5)
Control Mode   1   Control Mode   27   Ox2304~Ox2307(48965~48968)   P1~P4   Proportional band   1   Control Mode   1   Contro	14/ 44	
27         0x2304~0x2307(48965~48968)         P1~P4         Proportional band         1         I           28         0x2308~0x230B(48969~48972)         I1~I4         Integration time         1         I           29         0x230C~0x230F(48973~48976)         D1~D4         Differential time         1         I           30         0x2310~0x2313(48977~48980)         CP1~CP4         Control period         1         I           31         0x2314~0x2317(48981~48984)         DB1~DB2         Data bit control hysteresis         1         I           32         0x2318~0x231B(48985~48988)         AM1~AM4         Auto-Manual switch         1         I           Reserve           33         0x2324~0x2327(48997~49000)         ACT1~ACT4         Output type         1         F	R/W	
28	R/W	
29         0x230C~0x230F(48973~48976)         D1~D4         Differential time         1         I           30         0x2310~0x2313(48977~48980)         CP1~CP4         Control period         1         I           31         0x2314~0x2317(48981~48984)         DB1~DB2         Data bit control hysteresis         1         I           32         0x2318~0x231B(48985~48988)         AM1~AM4         Auto-Manual switch         1         I           Reserve           33         0x2324~0x2327(48997~49000)         ACT1~ACT4         Output type         1         F	R/W	
30   0x2310~0x2313(48977~48980)   CP1~CP4   Control period   1   1   31   0x2314~0x2317(48981~48984)   DB1~DB2   Data bit control hysteresis   1   1   32   0x2318~0x231B(48985~48988)   AM1~AM4   Auto-Manual switch   1   1   1   1   1   1   1   1   1	R/W	
31   0x2314~0x2317(48981~48984)   DB1~DB2   Data bit control hysteresis   1   1   32   0x2318~0x231B(48985~48988)   AM1~AM4   Auto-Manual switch   1   1   1   1   1   1   1   1   1	R/W	
32 0x2318~0x231B(48985~48988) AM1~AM4 Auto-Manual switch 1 Reserve 33 0x2324~0x2327(48997~49000) ACT1~ACT4 Output type 1 F		
Reserve 33 0x2324~0x2327(48997~49000) ACT1~ACT4 Output type 1 F	R/W	
33 0x2324~0x2327(48997~49000) ACT1~ACT4 Output type 1 F	R/W	
	D 044	
34  UXZ3Z6~UXZ3Z8(49UU1~49UU4)   PTT~PT4   Cooling start delay   1	R/W	-
	R/W	
	R/W	
Reserve		
	R/W	
37 0x2501(49474) BAD Communication baud 1	R	
38 0x2502(49475) PRTY Check bit selection 1	R	
39 0x2503(49476) DATC Data transmission sequence 1	R	3
40 0x2504(49477) LCK Password 1	R	
41   0x2505(49478)   NAME   Meter Name   1	R	

Note①: The register number is the address converted to decimal plus 1 and then the register identification code 4 is added in front; for example: the register number of the data address 0x2000 is 8192 + 1 = 8193 and then 4 is added in front, that is, the register number 48193; Related applications can be seen, such as Siemens S7-200 PLC.

Note ②: Channel status indication. When the data bit is 1, it means execution, and when it is 0, it means not executed.

D7	D6	D5	D4	D3	D2	D1	D0
	НННН	LLLL				AL1	OUT1

Note③: DTC communication data transmission sequence and response delay description

```
Reserve
DATC:
Byte transfer order: when it is 0, 1, 2, and when it is 1, 2, 1

### Reserve

### 16-bit CRC check code to get C program
```

```
unsigned int Get_CRC(uchar *pBuf, uchar num)
   \begin{array}{ll} unsigned \ i,j; \\ unsigned \ int \ wCrc = 0xFFFF; \\ for(i=0;i<num;i++) \end{array} 
                                  wCrc ^= (unsigned int)(pBuf[i]);
                                  for(j=0; j<8; j++)
                                                   if(wCrc & 1){wCrc >> = 1; wCrc ^= 0xA001; }
                                                                    wCrc >>= 1;
     return wCrc:
```

④:Alarm parameter and output logic diagram
Explanation of symbols: "☆" means HY . "▲" means alarm value, and "△" means SV value

Explanation of symbols. A means in , A means alaim value, and A means 39 value					
Alarm code	Alarm form	Alarm output Figure: The shaded area means the alarm action			
1	High limit alarm of absolute value	→			
2	Low limit alarm of absolute value	→ ☆ ↓ △ AL SV → PV			
3	High limit alarm of deviation	SV+AL PV			
4	Low limit alarm     of deviation	→ DV SV-AL SV			
5	Alarm outside upper / lower limit deviation	SV-AL SV SV+AL			
6	Alarm within upper / lower limit deviation	SV-AL SV SV+AL			

When the alarm value with deviation alarm is set to a negative number, it is treated as an absolute value.

#### ⑤:Alarm extension function table

9.3 taliii exteriolori tariotion table						
	AE11~AE14 Value	Alarm handling method when it displays HHHH/LLLL	Remark			
Power on,	0	0 Alarm status remains the same				
no alarm inhibition  Power on, alarm inhibition	1	Alarm forced output	condition is met, alarn			
	2	Alarm forced close	output immediately			
	3	Alarm status remains the same	After power on and before the PV value reaches			
	4 Alarm forced output		the SV for the first time, the			
			After that alarm work normally			

© : 0: running 1: stopping 2: auto-turning (upper computer read / write "0" means run, read / write "1" means stop, and read / write "2" means setting or starting auto-tuning)

## XIII. Version and Revision History

Date	Version	Revision content
2023.03.23	A/0 version	1st edition

If it is used in a way not specified in this manual, the protection function will be damaged. Manufacturer contact information: Sommy Automation Group Shares Co., Ltd Add: No.8 Minke West Rd, Shiqi District, Zhongshan, Guangdong, CN 528400 Contact:0086-760-23371800

Technical consultation contact: 0086-760-88722603 Web:https://www.sommy.com.cn